



Representation and Data Structures

We approximate entities with objects.

This approximation is biased

Entities-"things" in the real world we represent (*Rivers, buildings, soil types, wetlands*)

Objects-our representation in a data model



REPRESENTATION AND DATA STRUCTURES

We can get multiple objects from a single entity, e.g.,

- lake may be a •municipal water source •recreation area •flood control sink
- •wildlife habitat

We typically store different object types (even from the same entity) in different layers.







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Data Models Data model typically includes at least two parts – Coordinate data - pairs or triplets of numbers that define spatial location and extent of geographic objects Attribute data – complement coordinate data to define cartographic objects: text, numbers, images, or other "non-spatial" data Keys, labels, or other indices are used so that the coordinate and attribute data may be viewed, related, and manipulated together.















Attribute Data

- Attributes are often represented in tables . Each row corresponds to an individual spatial object, and each column corresponds to an attribute.
- Tables are organized and managed using a database management system.











Vector data model

- Point feature (0 dimension: no length, no width): Represents a single location. It defines map object too small to show as a line or area feature. A special symbol or label usually depicts a point location. (depends on scale)
- Line feature (1 dimension: no width): Represents a set of connected ordered coordinates representing the linear shape of a map object that may be too narrow to display as an area, such as a road, or a feature with no width, such as a contour line.











Road¶ Number§	Road¶ Type§	Surface§	Width§	Lanes§	Name§
1§	1§	Concrete§	60§	4§	Hwy 42
2§	2§	Asphalt§	48§	4§	N Main S
38	48	Asphalt§	326	28	Elm St





























Comparisons, raster v.s. vector					
	Vector	Raster			
Characteristics					
Positional Precision	Can be Precise	Defined by cell size			
Attribute Precision	Poor for continuous data	Good for continuous data			
Analytical Capabilities	Good for spatial query, adjacency, area, shape analyses. Poor for continuous data. Most analyses limited to intersections. Slower overlays.	Spatial query more difficult, good for local neighborhoods, continuous variable modeling. Rapid overlays.			
Data Structures	Often complex	Often quite simple			
Storage Requirements	Relatively small	Often quite large			
Coordinate	Usually well-supported	Often difficult, slow			
Network Analyses	Easily handled	Often difficult			
Output Quality	Very good, map like	Fair to poor - aliasing			

