COA 690/790 GIS in Marine Science

### Data Entry Getting coordinates and attributes into our GIS

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### DATA SOURCES, INPUT, AND OUTPUT

Manually digitizing from image or map sources

- manually drawn maps
- legal records
- · coordinate lists with associated tabular data
- Aerial photographs

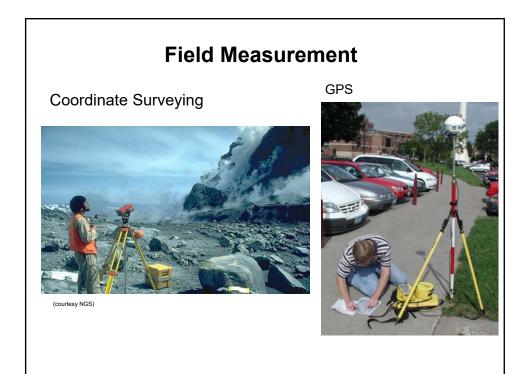
Field coordinate measurement

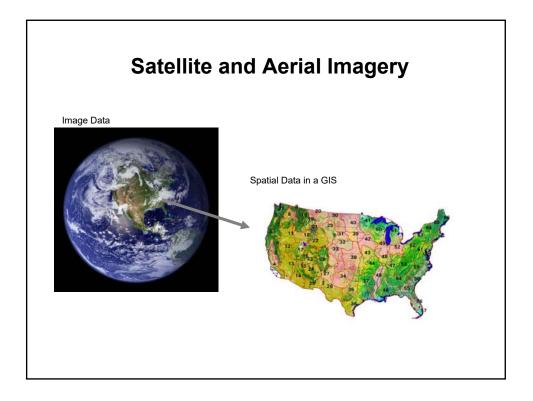
- Coordinate Surveying
- GPS

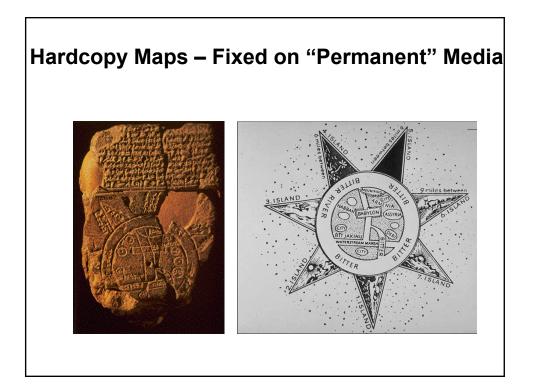
Image data

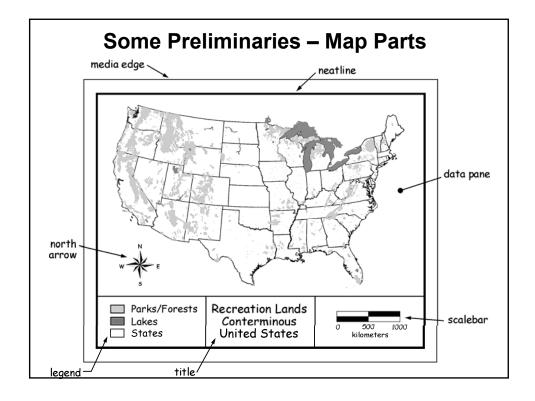
- Manual or automated classification
- direct raster data entry

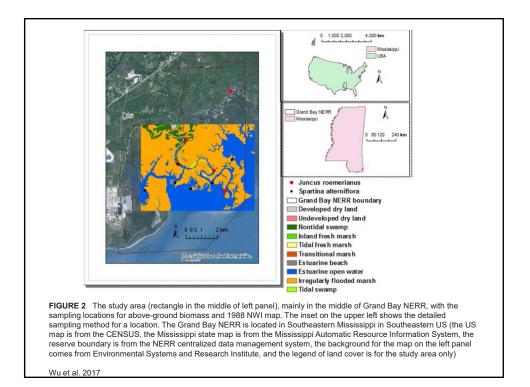


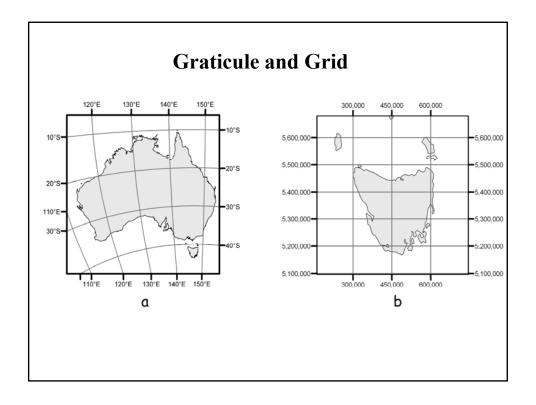


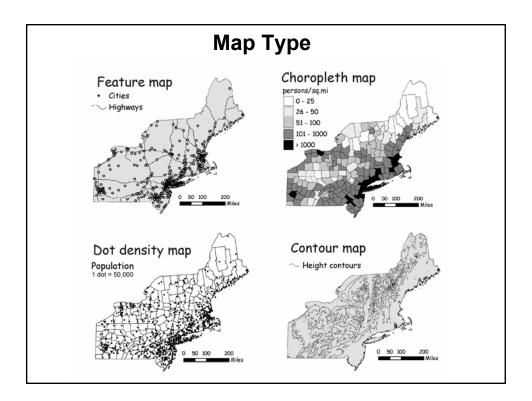




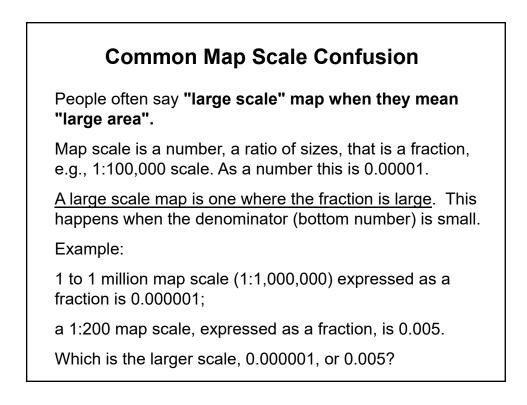








Map Scale
The ratio of : a distance on a map to a distance on the ground
Commonly reported as a:
Unitless ratio : 1: 100,000
Unit ratio : e.g., four inches to one mile
Scale bar: 0 50 100 200



## **Common Map Scale Misperception**

If you have two map sheets which are 10 inches across, the 1:1,000,000 map (which is small scale) covers a distance of 10,000,000 inches

The 1:200 map (large scale) covers about 200\*10=2000 inches.

Remember, <u>larger scale maps cover less area, but</u> <u>show more detail.</u>

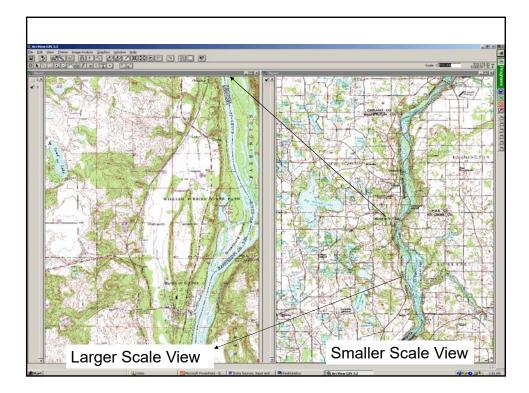
### Map Scale

"Scale" of GIS data

**Digital spatial data have no scale**. An input map had a scale, but many data don't come from maps, e.g., GPS data.

Spatial data in a GIS may be displayed on-screen at a broad ranges of scales – there is no one scale.

We must think of a source scale, if it exists And A display scale, the ratio of ground to on screen size



#### **Determining Scale on Source Materials**

If map scale is not available, the best method is to measure paired distances,

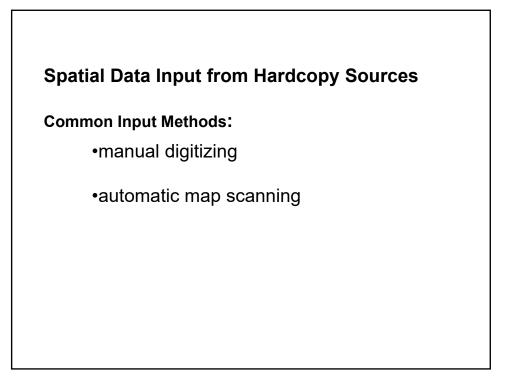
e.g., the distance between two road intersections on the map is 4.3 cm,

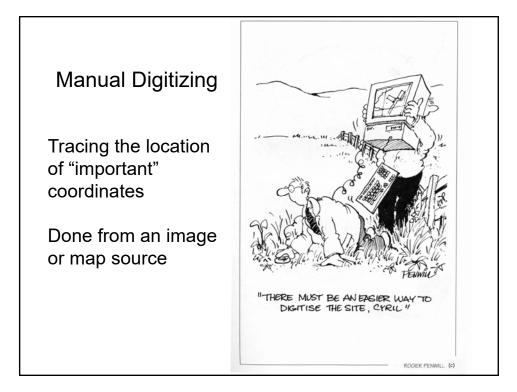
field measurements between the same two road intersections shows the distance to be 1220 meters. The scale of the map is then

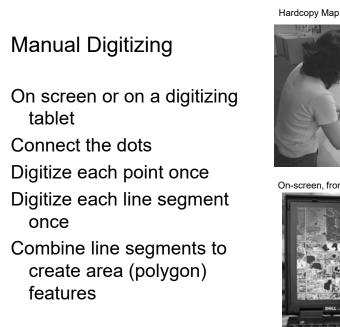
map distance / ground distance, or

{ 4.3cm \*1m/100cm } / 1220 m or

0.043 / 1,220 = 1 / 28,372









On-screen, from digital image



### **Manual Digitization**

Connect the dots - lines or points with an electrically sensitized puck.

Wire grid typically used to identify puck location on tablet

Puck location recorded relative to an arbitrary table coordinate system

Points locations are signaled by pressing buttons on the puck

Accuracies of between 0.01 and 0.001 inches

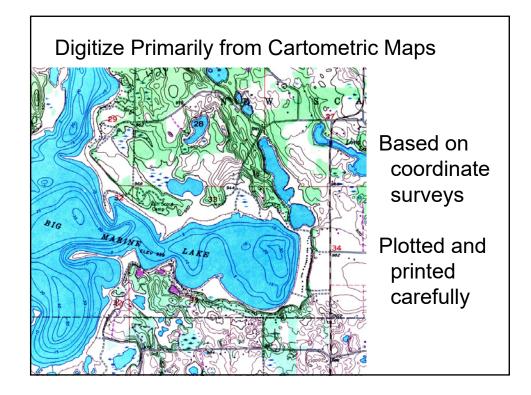


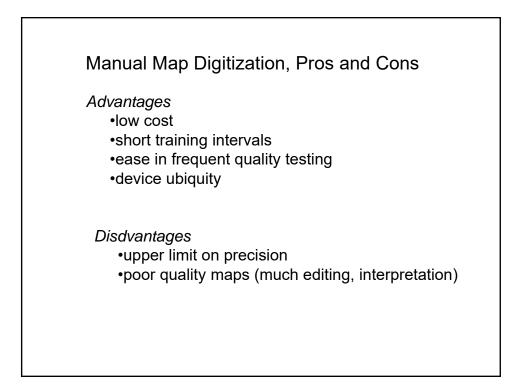
# Manual Digitizing Process from hardcopy map:

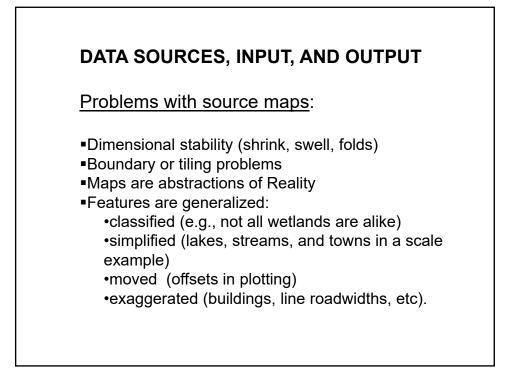
- 1. Fix map to digitizer table
- 2. Digitize control points (tics, reference points, etc.) of known location
- 3. Digitize feature boundaries in <u>stream</u> or <u>point</u> mode
- 4. Proof, edit linework
- 5. Transform or register to known system (may also be done at start)
- 6. Re-edit, as necessary

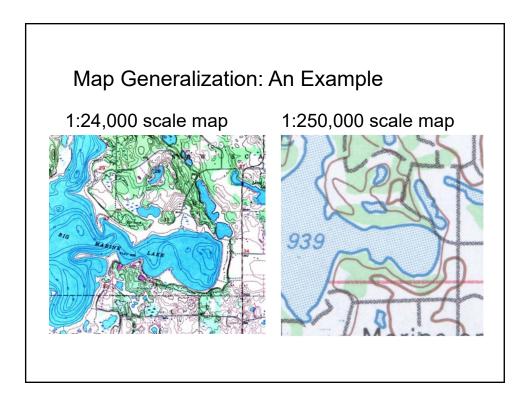
# Manual Digitizing Process from digital image:

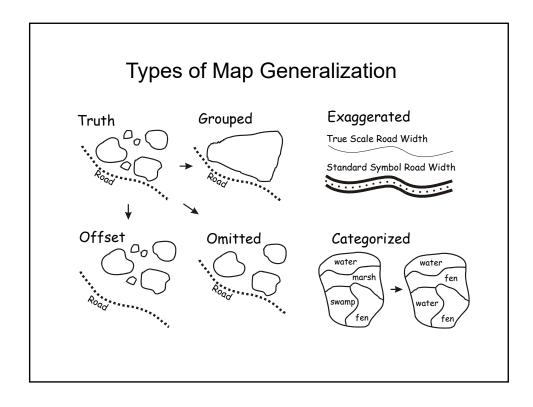
- 1. Scan map or image
- 2. If image not referenced, collect ground coordinates of control points
- 3. Digitize control points (tics, reference points, etc.) of known location
- 4. Transform (register) image to known coordinate system
- 5. Digitize feature boundaries in <u>stream</u> or <u>point</u> mode
- 6. Proof, edit linework
- 7. Re-edit, as necessary

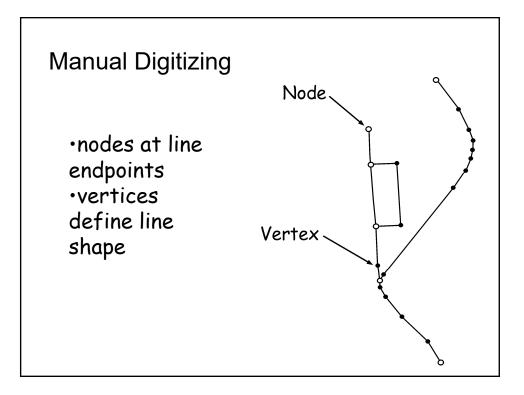


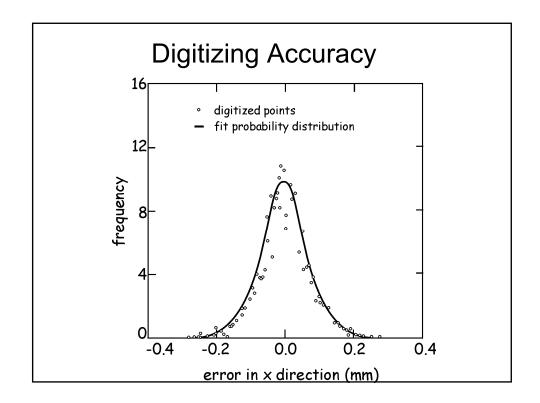


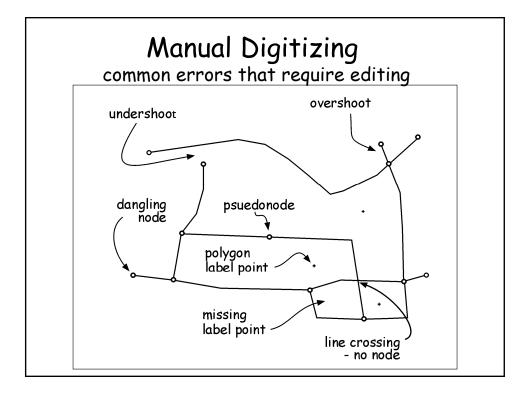












### Editing

Manual editing:

Line and point locations are adjusted on a graphic display, pointing and clicking with a mouse or keyboard. Most controlled, most time-consuming .

Interactive rubbersheeting:

Anchor points are selected, again on the graphics screen, and other points selected and dragged around the screen. All lines and points except the anchor points are interactively adjusted.

### Editing

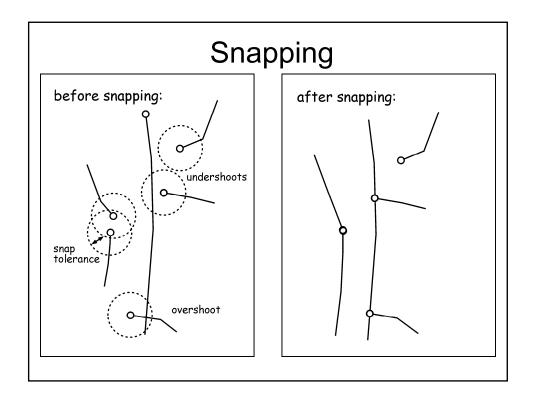
<u>Attribute consistency analysis</u>: Identify contradictory theme types in different data layers, and resolve

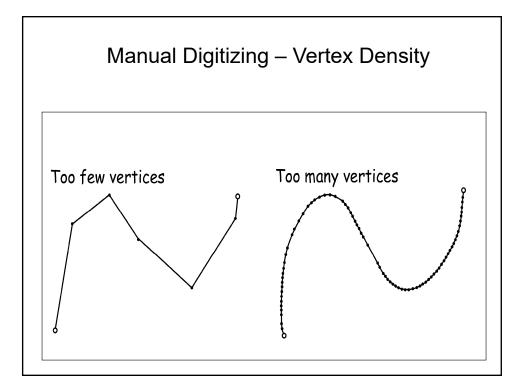
Line snapping:

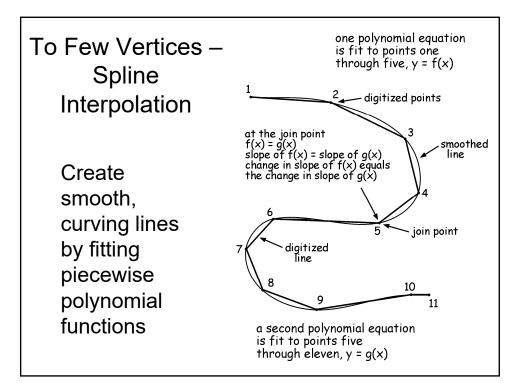
When a vertex or node is "close" to a line or end point, the lines are "snapped" together

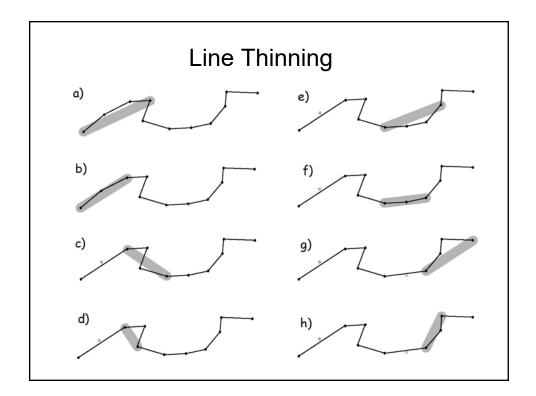
### Point snapping:

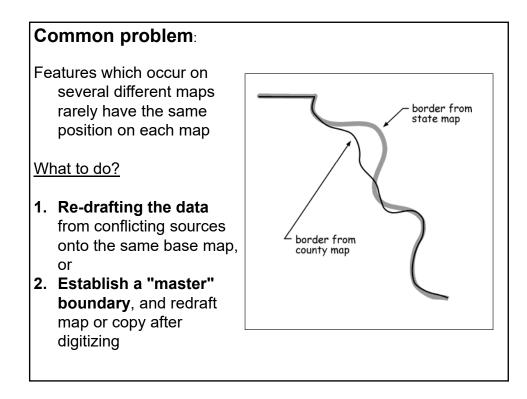
Points which fall within a specified distance of each other are snapped (typically, on point eliminated).

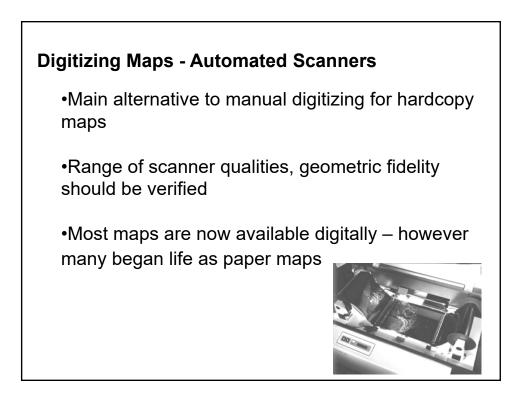


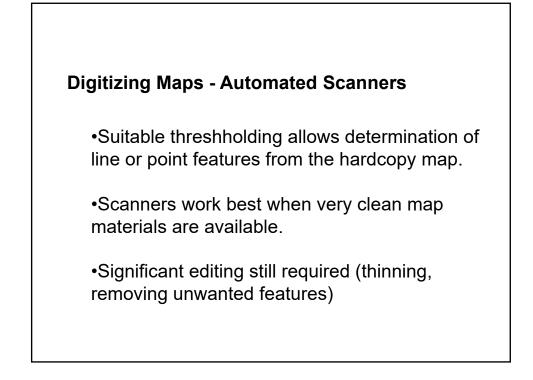


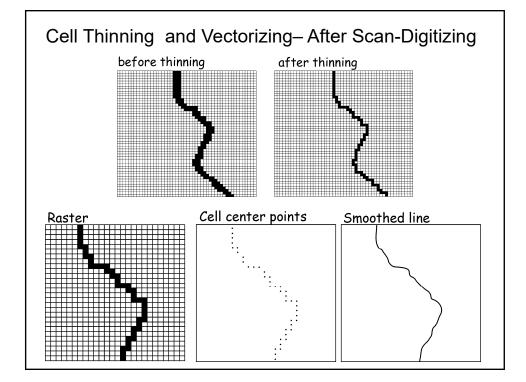












# Coordinate Transformation

- Also referred as registration
- Control points
- The affine transformation  $E = T_{r} + a_{r}x + a_{r}y$

$$\mathbf{E} = \mathbf{I}_{\mathbf{E}} + \mathbf{a}_1 \mathbf{X} + \mathbf{a}_2 \mathbf{y}$$

$$N = T_N + b_1 x + b_2 y$$

• Minimize RMSE